

Group theory

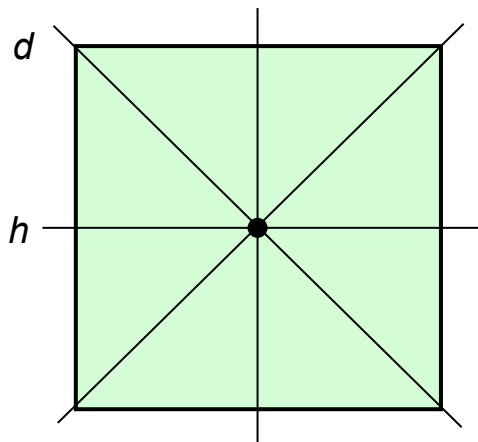
Definition: group \mathcal{G} is a set $\mathcal{G} = \{a, b, c, \dots\}$ with a product \cdot

$$\begin{array}{l} a \in \mathcal{G} \\ b \in \mathcal{G} \end{array} \quad \rightarrow \quad a \cdot b \in \mathcal{G} \quad \text{associative } (a \cdot b) \cdot c = a \cdot (b \cdot c)$$

identity $E \in \mathcal{G}$ with $E \cdot a = a \cdot E = a$

inverse $a \in \mathcal{G} \rightarrow a^{-1} \in \mathcal{G}$ with $a^{-1} \cdot a = a \cdot a^{-1} = E$

Example: C_{4v} symmetry operation of square



$$C_{4v} = \{E, C_4, C_4^{-1}, C_2, \sigma_h, \sigma'_h, \sigma_d, \sigma'_d\}$$

$$C_4 \cdot C_4 = C_2 \quad \underbrace{\sigma_h \cdot C_4 = \sigma'_d \quad C_4 \cdot \sigma_h = \sigma_d}$$

$$\sigma_h \cdot C_4 \neq C_4 \cdot \sigma_h$$

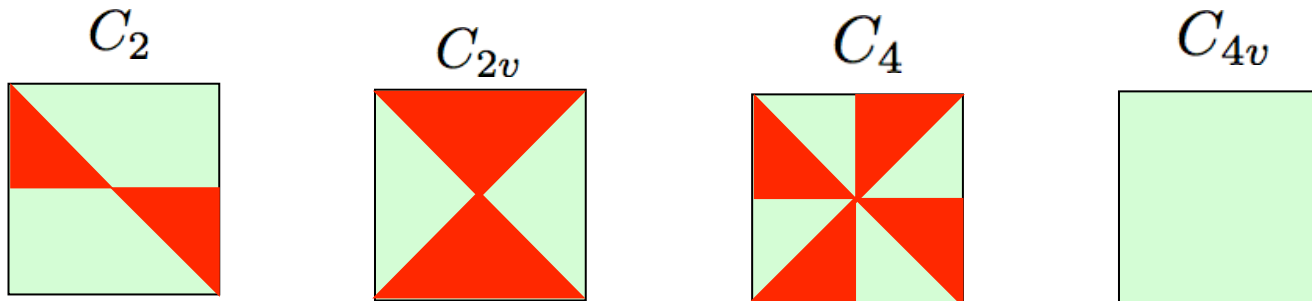
non-abelian

Group theory

subgroup: group \mathcal{G}' subset of \mathcal{G}

$$\mathcal{G}' \subset \mathcal{G}$$

examples:
$$\left. \begin{aligned} C_4 &= \{E, C_4, C_4^{-1}, C_2\} \\ C_{2v} &= \{E, C_2, \sigma_h, \sigma'_h\} \\ C_2 &= \{E, C_2\} \end{aligned} \right\} \subset C_{4v}$$



number of elements: $|\mathcal{G}'|$ divides $|\mathcal{G}|$

Group representation

linear transformations: consider n -dimensional vector space $\mathcal{V} = \{|1\rangle, |2\rangle, \dots, |n\rangle\}$

transformations on \mathcal{V} by unitary $n \times n$ -matrices $|k'\rangle = g|k\rangle = \sum_j M_{k'j}(g)|j\rangle$

matrices \hat{M} satisfies all properties of a group

representation

mapping (homomorphism) of group \mathcal{G} on $n \times n$ -matrices in \mathcal{V}

$g \rightarrow \hat{M}(g)$ conserving group structure \rightarrow representation of \mathcal{G}

$$\hat{M}(E) = \hat{1}_{n \times n} \quad \hat{M}(g^{-1}) = \hat{M}(g)^{-1}$$

equivalent representations: $\hat{M}'(g) = \hat{U}\hat{M}(g)\hat{U}^{-1}$ basis transformation \hat{U}

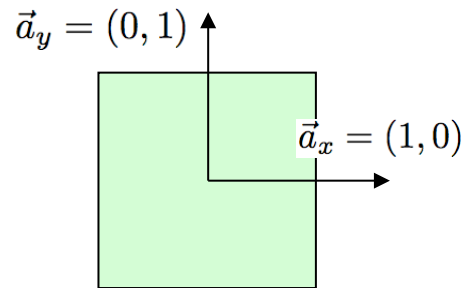
characters: $\chi(g) = \text{tr}\hat{M}(g)$ independent of basis

Group representation

irreducible representation: independent of basis $\{\hat{M}(g)\}$ connects whole \mathcal{V}

trivial representation: $n = 1 \quad g \rightarrow \hat{M}(g) = 1$

example: C_{4v} \hat{M} transformation of $\{\vec{a}_x, \vec{a}_y\}$



$$\begin{aligned}
 E &\rightarrow \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} & C_4 &\rightarrow \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} & C_4^{-1} &\rightarrow \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} & C_2 &\rightarrow \begin{pmatrix} -1 & 0 \\ 0 & -1 \end{pmatrix} \\
 \sigma_h &\rightarrow \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} & \sigma'_h &\rightarrow \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix} & \sigma_d &\rightarrow \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} & \sigma'_d &\rightarrow \begin{pmatrix} 0 & -1 \\ -1 & 0 \end{pmatrix}
 \end{aligned}$$

character
table

	E	C_4	C_4^{-1}	C_2	σ_h	σ'_h	σ_d	σ'_d	basis function
A_1	1	1	1	1	1	1	1	1	1
A_2	1	1	1	1	-1	-1	-1	-1	$xy(x^2 - y^2)$
B_1	1	-1	-1	1	1	1	-1	-1	$x^2 - y^2$
B_2	1	-1	-1	1	-1	-1	1	1	xy
E	2	0	0	-2	0	0	0	0	$\{x, y\}$

Group representation & quantum mechanics

symmetry operations of Hamiltonian form a group $\mathcal{G} = \{\hat{S}_1, \dots\}$
 Hilbertspace is vector space $\{|\psi_1\rangle, \dots\}$

stationary states: $\mathcal{H}|\phi_n\rangle = \epsilon_n|\phi_n\rangle$

$$[\hat{S}, \mathcal{H}] = 0 \quad \rightarrow \quad \mathcal{H}\hat{S}|\phi_n\rangle = \hat{S}\mathcal{H}|\phi_n\rangle = \epsilon_n\hat{S}|\phi_n\rangle$$

$|\phi_n\rangle$ and $|\phi'_n\rangle = \hat{S}|\phi_n\rangle$ degenerate

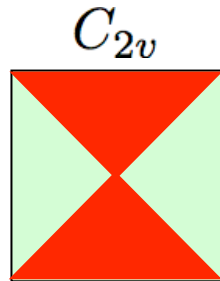
degenerate states form a vector space with an irred. representation of \mathcal{G}

$$\{|\phi_1\rangle, \dots, |\phi_m\rangle\} \quad \text{with} \quad \hat{S}|\phi_k\rangle = \sum_{k'=1}^m M_{kk'}|\phi_{k'}\rangle$$

dimension m of representation = degeneracy

Group representation & quantum mechanics

symmetry lowering $C_{4v} \rightarrow C_{2v}$



	E	C_2	σ_h	σ'_h	basis
A'_1	1	1	1	1	1
A'_2	1	-1	1	-1	x
B'_1	1	1	-1	-1	xy
B'_2	1	-1	-1	1	y

C_{4v}	C_{2v}
A_1	A'_1
A_2	B'_1
B_1	A'_1
B_2	B'_1
E	$A'_2 \oplus B'_2$

splitting of degeneracy through symmetry lowering

