

② Lorentz & Poincaré symmetries in QFT

2.1. Lie groups

Lie group: group elements g depend in continuous and differentiable way on a set of real parameters $w^a, a \in \{1, \dots, N\}$

→ choose w^a s.t. $g(w^a=0) = g(0) = e$
↑ unit element of group

A (linear) representation R of the group:

$g \mapsto D_R(g)$
↑ abstract group element linear operator

s.t. $D_R(1) = 1$

$$D_R(g_1) \cdot D_R(g_2) = D_R(g_1 \cdot g_2)$$

Typically: for finite dimensional representation, D_R is $n \times n$ matrix

trsf of ϕ^i : $\phi^i \rightarrow (D_R(g))^i_j \phi^j$

if ϕ^i transform under representation R

irreducible representation: no invariant subspace (all components mix)

For infinitesimal w^a , $D_R(g(w^a)) \approx 1 + i w^a T_R^a$

$$T_R^a \equiv -i \frac{\partial D_R(w^a)}{\partial w^a} \Big|_{w=0} \quad \text{generator of group in representation } R$$

Given T_R^a , for finite w^a : $D_R(g(w^a)) = e^{i w^a T_R^a}$

Lie algebra of group:

$$[T_{(R)}^a, T_{(R)}^b] = i f^{abc} T_{(R)}^c$$

↑
structure constants
→ independent of representation R!

structure constants → Lie algebra → Lie group

To find matrix representations of group, find solutions

to $[T^a, T^b] = i f^{abc} T^c$

example: rotations in \mathbb{R}^3

→ 3 parameters $\omega^a : \omega^1, \omega^2, \omega^3$

$$D_F(g(\omega_1=0, \omega_2=0, \omega_3)) = \begin{pmatrix} \cos \omega_3 & \sin \omega_3 & & \\ -\sin \omega_3 & \cos \omega_3 & & \\ & & 1 & \\ & & & 1 \end{pmatrix} \quad \begin{matrix} \text{(fundamental rep. of)} \\ \text{rotation about z(3) axis} \end{matrix}$$

$$\overline{T}_F^3 = -i \left. \frac{\partial D_F(\omega)}{\partial \omega_3} \right|_{\omega=0} = \begin{pmatrix} 0 & -i & & \\ i & 0 & & \\ & & 0 & \\ & & & 0 \end{pmatrix} \quad (= J_F^3 \text{ notation})$$

$$[J^i, J^j] = i \epsilon^{ijk} J^k \quad \text{Lie algebra satisfied by } J_F^3$$

D_F : fundamental rep. → vectors \vec{x} (under rotations)

trivial representation: $J_R^i (= T_R^i) = 0$ (Lie algebra satisfied)

→ $D_R = 1$ → scalars (under rot.)

Spinor representation $J_S^i = \frac{\sigma^i}{2}$ (Lie algebra satisfied)

→ spin 1/2

can classify quantities according to representation they transform

under for rotations → generalize to Lorentz transf.

2.2. Lorentz group

(homogeneous) LT : $x^\mu \rightarrow x'^\mu = \Lambda^\mu_\nu x^\nu$

defined by requirement that $g_{\mu\nu} x^\mu x^\nu (= t^2 - \vec{x}^2)$ invariant

$$\rightarrow g_{\mu\nu} x'^\mu x'^\nu = g_{\mu\nu} \Lambda^\mu_\rho x^\rho \Lambda^\nu_\sigma x^\sigma \stackrel{!}{=} g_{\rho\sigma} x^\rho x^\sigma$$

$$g_{\mu\nu} \Lambda^\mu_\rho \Lambda^\nu_\sigma = g_{\rho\sigma} \quad \text{or} \quad \Lambda^T \cdot g \cdot \Lambda = g$$

- (i) $(\det \Lambda)^2 = 1$ $\det \Lambda = +1$ proper LT (connected to identity)
- $\det \Lambda = -1$ improper LT (time reversal, parity)

$$(ii) \quad g_{\mu\nu} \Lambda^\mu_0 \Lambda^\nu_0 = 1 = (\Lambda^0_0)^2 - \sum_i (\Lambda^i_0)^2$$

$$\Lambda^0_0 \geq 1 \quad \text{orthochronous LT}$$

$$\Lambda^0_0 \leq -1 \quad \text{non-orthochronous LT}$$

proper orthochronous LT are connected to identity

$$\Lambda^\mu_\nu = g^\mu_\nu + \omega^\mu_\nu \quad \text{with} \quad \omega^{\mu\nu} = -\omega^{\nu\mu} \quad (6 \text{ parameters})$$

\rightarrow form a subgroup (Lie group)

(often sloppy language : LT means prop. orth. LT)

any LT that is not proper & orthochronous can be written as a prop. orth. LT times \mathcal{P} , \mathcal{T} or \mathcal{PT}

$$\mathcal{P} : \text{parity} \quad \mathcal{P}^\mu_\nu = \begin{pmatrix} 1 & & & \\ & -1 & & \\ & & -1 & \\ & & & -1 \end{pmatrix} \quad (t, \vec{x}) \rightarrow (t, -\vec{x})$$

$$\mathcal{T} : \text{time reversal} \quad \mathcal{T}^\mu_\nu = \begin{pmatrix} -1 & & & \\ & 1 & & \\ & & 1 & \\ & & & 1 \end{pmatrix} \quad (t, \vec{x}) \rightarrow (-t, \vec{x})$$

\mathcal{P} & \mathcal{T} are not connected to identity

\rightarrow treated separately

generator of (proper, orthochronous) LT : $J_{\mathbb{R}}^{\mu\nu}$

set of quantities ϕ^i , $i=1 \dots N$ transforms in representation \mathbb{R} of dim. N under LT

$$\rightarrow \phi^i \rightarrow \phi'^i = \left(e^{-\frac{i}{2} \omega_{\mu\nu} J_{\mathbb{R}}^{\mu\nu}} \right)^i_j \phi^j$$

convention: $\frac{1}{2}$ due to "double counting" in sum

$$= \phi^i + \underbrace{\left(\frac{-i}{2} \omega_{\mu\nu} (J_{\mathbb{R}}^{\mu\nu})^i_j \right)}_{\Delta\phi^i} \phi^j$$

consider vector representation $\phi^i \rightarrow V^{\rho}$

Under LT : $V^{\rho} \rightarrow V'^{\rho} = \Lambda^{\rho}_{\sigma} V^{\sigma} = (g^{\rho}_{\sigma} + \omega^{\rho}_{\sigma}) V^{\sigma}$

$$\Rightarrow \Delta V^{\sigma} = \omega^{\rho}_{\sigma} V^{\rho} = \left(\frac{-i}{2} \right) \omega_{\mu\nu} (J_{\mathbb{V}}^{\mu\nu})^{\rho}_{\sigma} V^{\rho}$$

compare: $(J_{\mathbb{V}}^{\mu\nu})^{\rho}_{\sigma} = i (g^{\mu\rho} g^{\nu\sigma} - g^{\nu\rho} g^{\mu\sigma})$

can use explicit form of $(J_{\mathbb{V}}^{\mu\nu})^{\rho}_{\sigma}$ to compute commutators

Lie algebra of $SO(3,1)$

$$[J^{\mu\nu}, J^{\rho\kappa}] = i (g^{\mu\kappa} J^{\nu\rho} + g^{\nu\rho} J^{\mu\kappa} - g^{\nu\kappa} J^{\mu\rho} - g^{\mu\rho} J^{\nu\kappa})$$

not only for $J_{\mathbb{V}}^{\mu\nu}$, but in all representations!

rearrange the 6 generators as follows:

$$J^i = \frac{1}{2} \epsilon^{ijk} J^{jk}$$

$$K^i = J^{i0}$$

$$[J^i, J^j] = i \epsilon^{ijk} J^k \quad (\text{ang. momentum})$$

$$[J^i, K^j] = i \epsilon^{ijk} K^k \quad (K: \text{spatial vector})$$

$$[K^i, K^j] = -i \epsilon^{ijk} J^k$$

Rewrite LT in terms of "new" generators:

$$\begin{aligned} \frac{1}{2} \omega_{\mu\nu} J^{\mu\nu} &= \omega_{12} J^{12} + \omega_{13} J^{13} + \omega_{23} J^{23} + \left(\sum_i \right) \omega_{i0} J^{i0} \\ &\equiv \vec{\theta} \cdot \vec{J} - \vec{\eta} \cdot \vec{K} = \theta^i J^i - \eta^i K^i \end{aligned}$$

with $\theta^i = \frac{1}{2} \epsilon^{ijk} \omega^{jk}$ (i.e. $\theta^1 = \omega^{23} = \omega_{23}$ + cyclic)
angles of rotation

$\eta^i = \omega^{i0} = -\omega_{i0}$ boost parameters

$$\rightarrow D_R(\Lambda) = e^{-i \vec{\theta} \cdot \vec{J}_R + i \vec{\eta} \cdot \vec{K}_R} = e^{-\frac{i}{2} \omega_{\mu\nu} J_R^{\mu\nu}}$$

will be useful for spinor representations

2.3. Tensor representations

Construct representations from vector representation

$$(J_{\nu}^{\mu\nu})^{\rho\sigma} = i (g^{\mu\rho} g^{\nu\sigma} - g^{\nu\rho} g^{\mu\sigma})$$

Of course there is the scalar representation $J_{sc}^{\mu\nu} = 0$ (trivial)

$$\rightarrow D(\Lambda) = 1 \quad S \rightarrow S' = D(\Lambda)S = S$$

Vector rep. (as in 2.2) $V \rightarrow V' = D(\Lambda) \cdot V \Leftrightarrow V'^{\rho} = \Lambda^{\rho}_{\sigma} V^{\sigma}$
$$e^{\frac{i}{2} \omega_{\mu\nu} J_{\nu}^{\mu\nu}}$$

Generalize to arbitrary tensors, e.g. tensor of rank 2

$$T^{\mu\nu} \rightarrow T'^{\mu\nu} = \Lambda^{\mu}_{\rho} \Lambda^{\nu}_{\sigma} T^{\rho\sigma}$$

16 components \rightarrow 16 dimensional representation, but reducible!

Split into antisymmetric $A^{\mu\nu} = \frac{1}{2} (T^{\mu\nu} - T^{\nu\mu})$ (6 comp)

and symmetric $S^{\mu\nu} = \frac{1}{2} (T^{\mu\nu} + T^{\nu\mu})$ part (10 comp)

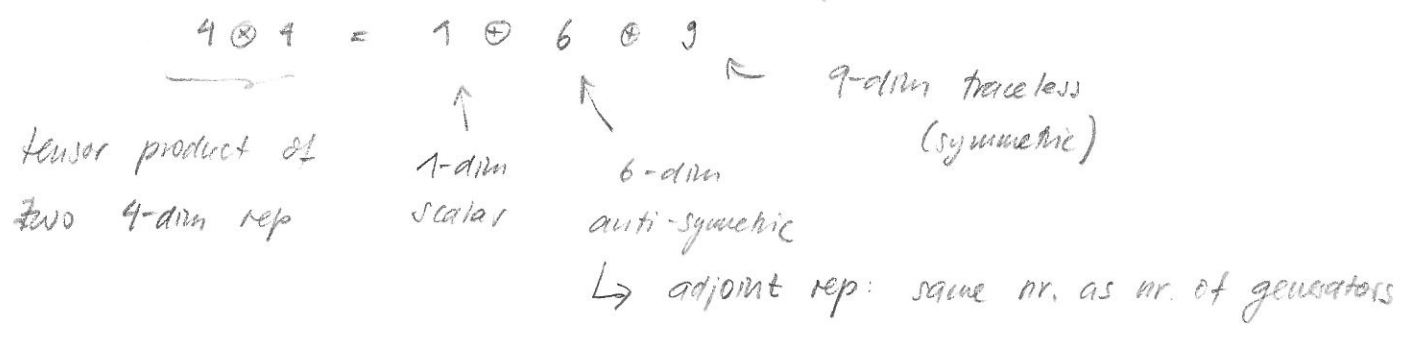
These properties remain under LT!

In addition trace of $S^{\mu\nu}$ is L-invariant

$$S = g_{\mu\nu} S^{\mu\nu} \rightarrow g_{\mu\nu} \Lambda^{\mu}_{\rho} \Lambda^{\nu}_{\sigma} S^{\rho\sigma} = g_{\rho\sigma} S^{\rho\sigma} = S$$

def. of LT!

Tensor of rank 2 has rep.



There are 2 invariant tensors (same coefficient in each inertial frame)

$$(i) \quad g^{\mu\nu} = \begin{pmatrix} 1 & & & \\ & -1 & & \\ & & -1 & \\ & & & -1 \end{pmatrix} \quad g^{\mu\nu} \rightarrow g'^{\mu\nu} = \Lambda^\mu_{\ \rho} \Lambda^\nu_{\ \sigma} g^{\rho\sigma} = g^{\mu\nu}$$

def. of L-transf.

(ii) $\epsilon^{\mu\nu\rho\sigma}$ totally antisymmetric tensor

$$\epsilon^{\mu\nu\rho\sigma} \rightarrow \epsilon'^{\mu\nu\rho\sigma} = \Lambda^\mu_{\ \mu'} \Lambda^\nu_{\ \nu'} \Lambda^\rho_{\ \rho'} \Lambda^\sigma_{\ \sigma'} \epsilon^{\mu'\nu'\rho'\sigma'} = (\det \Lambda) \epsilon^{\mu\nu\rho\sigma}$$

= 1 for proper LT!

We know how tensor transform under LT \rightarrow deduce how they transform under rotations $SO(3)$ \rightarrow get information on ang. mom.

scalar: trivial transf. under $SO(3)$ \rightarrow ang. mom $j=0$

V^μ : $V^0 \rightarrow$ trivial $\rightarrow j=0$

$V^i \rightarrow$ irreducible 3-dim rep of $SO(3)$ $\rightarrow j=1$

V^μ : $0 \oplus 1$

$T^{\mu\nu}$: $(0 \oplus 1) \otimes (0 \oplus 1)$

$$= (0 \otimes 0) \oplus (0 \otimes 1) \oplus (1 \otimes 0) \oplus (1 \otimes 1)$$

$$= \underbrace{0}_{S} \oplus \underbrace{1 \oplus 1}_{A^{\mu\nu}} \oplus \underbrace{(0 \oplus 1 \oplus 2)}_{\text{traceless } S^{\mu\nu}}$$

S

$A^{\mu\nu}$

traceless $S^{\mu\nu}$

(example $F^{\mu\nu} \Rightarrow \vec{E}, \vec{B}$)

In general tensors of rank N contains up to $j=N$

2.4. Spinor Representations

recall subset of Lorentz algebra $[J^i, J^k] = i \epsilon^{ijk} J^k$

→ representation by Pauli matrices $\frac{\sigma^i}{2} = J^i$

→ spin $1/2$,
 ↓
 spinors $\psi_\alpha \alpha \in \{1, 2\}$ } higher spin with tensor products such as
 $\frac{1}{2} \otimes \frac{1}{2} = 0 \oplus 1$ et.

How to generalize this to the relativistic case?

→ spinors in relativity

define $\vec{J}_\pm = \frac{1}{2} (\vec{J} \pm i \vec{K})$ (yet another combination to unite the 6 generators)

Lie algebra becomes:

$$[J_+^i, J_+^j] = i \epsilon^{ijk} J_+^k$$

$$[J_-^i, J_-^j] = i \epsilon^{ijk} J_-^k$$

$$[J_+^i, J_-^j] = 0$$

} 2 commuting copies of $su(2)$

- Representations can be labelled by j_+ and j_- : (j_-, j_+)
- dimension of (j_-, j_+) representation is $(2j_- + 1)(2j_+ + 1)$
- $\vec{J} = \vec{J}_+ + \vec{J}_-$, possible spin states in representation (j_-, j_+) are $|j_+ - j_-|$ to $j_+ + j_-$ (addition of ang. mom.)

simplest case: $(j_-, j_+) = (0, 0)$

$$\vec{J} = \vec{J}_+ + \vec{J}_- = 0$$

$$\vec{K} = -i(\vec{J}_+ - \vec{J}_-) = 0$$

} → scalar representation

$(j_-, j_+) = (0, \frac{1}{2})$ right-handed Weyl spinor ψ_R

$\vec{j}^+ \rightarrow 2\text{-dimensional} \Rightarrow \vec{j}^+ = \frac{\vec{\sigma}}{2}$

$\vec{j}^- \rightarrow 1\text{ dimensional} \Rightarrow \vec{j}^- = 0$

$$\left. \begin{aligned} \vec{J} &= \vec{j}_+ + \vec{j}_- = \frac{1\vec{\sigma}}{2} \\ \vec{K} &= -i(\vec{j}_+ - \vec{j}_-) = -i\frac{1\vec{\sigma}}{2} \end{aligned} \right\} D(\Lambda) = e^{-i\vec{\sigma}\vec{J} + i\vec{\eta}\vec{K}} = e^{(-i\vec{\sigma} + \vec{\eta})\frac{\vec{\sigma}}{2}}$$

An object that transforms under LT as

$\psi_R \rightarrow \psi'_R = e^{(-i\vec{\sigma} + \vec{\eta})\frac{\vec{\sigma}}{2}} \psi_R \equiv D_R(\Lambda)\psi_R$

is called a right-handed Weyl spinor. It has 2 components

$(\psi_R)_\alpha \quad \alpha \in \{1, 2\}$

(*) $\left(\begin{array}{l} \text{in literature, often } \vec{j} \text{ used} \\ \text{just notation, to indicate right-handed!} \end{array} \right)$

$(j_-, j_+) = (\frac{1}{2}, 0)$ left-handed Weyl spinor ψ_L

now $\vec{j}^+ = 0$ and $\vec{j}^- = \frac{1\vec{\sigma}}{2}$

$\Rightarrow \vec{J} = \frac{1\vec{\sigma}}{2}, \quad \vec{K} = +i\frac{1\vec{\sigma}}{2} \Rightarrow D(\Lambda) = e^{(-i\vec{\sigma} - \vec{\eta})\frac{\vec{\sigma}}{2}}$

An object that transforms under LT as

$\psi_L \rightarrow \psi'_L = e^{(-i\vec{\sigma} - \vec{\eta})\frac{\vec{\sigma}}{2}} \psi_L \equiv D_L(\Lambda)\psi_L$

is called a left-handed Weyl spinor. 2 components $(\psi_L)_\alpha$

Note $(\frac{1}{2}, 0)$ and $(0, \frac{1}{2})$ are inequivalent representations

i.e. \nexists matrix S , s.t. $D_R(\Lambda) = S D_L(\Lambda) S^{-1}$

rather $D_R(\Lambda) = S D_L^*(\Lambda) S^{-1}$ with $S = i\sigma_2$

(use $\sigma_2 \vec{\sigma} \sigma_2 = -\vec{\sigma}$ to show this)

define charge conjugation (name will become clear later)

$\psi_L^c \equiv i\sigma_2 \psi_L^*$ claim: this is a right-handed spinor

check: $\psi_L^c \rightarrow i\sigma_2 (D_L(\Lambda) \psi_L)^* = \underbrace{i\sigma_2 D_L^*(\Lambda)}_{D_R(\Lambda)} (i\sigma_2)^{-1} \underbrace{(i\sigma_2) \psi_L^*}_{\psi_L^c}$

Note: factor i convention

similar: $\psi_R^c \equiv -i\sigma_2 \psi_R^*$ is a left-handed Weyl spinor

Note: left-handed & right handed refer to transformation property, but is related to projection of spin along momentum (helicity)
 right-handed: $\vec{s} \uparrow \uparrow \vec{p}$
 left-handed: $\vec{s} \uparrow \downarrow \vec{p}$ } \rightarrow later

for $m=0$ helicity (\rightarrow chirality) is L.H.V!

Dirac spinor (\rightarrow section 3)

under parity: $\vec{R} \rightarrow -\vec{R}$ (vector) and $\vec{J} \rightarrow \vec{J}$ (axial vector)
 $\rightarrow \vec{J}_+ \leftrightarrow \vec{J}_-$ representation $(j_-, j_+) \leftrightarrow (j_+, j_-)$
 not basis for parity transformation.

if theory invariant under parity (e.g. QED) it is useful to work with fields which provide rep under (p&o) LT and parity

\rightarrow Dirac $\psi_\alpha = \begin{pmatrix} \psi_L \\ \psi_R \end{pmatrix}$
 $\alpha = 1 \dots 4$
 LT: $\psi \rightarrow \begin{pmatrix} D_L(\Lambda) & 0 \\ 0 & D_R(\Lambda) \end{pmatrix} \psi$
 P: $\psi \rightarrow \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \psi$ $\psi_L \leftrightarrow \psi_R$

if theory not invariant under parity (e.g. weak interaction) work with Weyl spinors

2.5. Field transformations

So far, we have considered transformations at a fixed point P
i.e. for $x \rightarrow x' = \Lambda x$ we have considered $\phi(x) \rightarrow \phi'(x') = D(\Lambda) \phi(x)$

scalar: $\phi'(x') = 1 \cdot \phi(x)$

vector: $V'^{\mu}(x') = \Lambda^{\mu}_{\nu} V^{\nu}(x)$

(Left-handed) Weyl spinor: $(\psi_L)'_{\alpha}(x') = \left[e^{(-i\vec{\theta} - \vec{\eta}) \cdot \frac{\vec{\sigma}}{2}} \right]_{\alpha}^{\beta} (\psi_L)_{\beta}(x)$

These were all finite-dimensional representations (if linear)

⌈ Note: these rep are not unitary, e.g. "missing" i in the $\vec{\eta} \cdot \frac{\vec{\sigma}}{2}$ term. Related to fact that Lorentz group is not compact (rotations are, but boosts not) ⌋

For a field (e.g. a scalar field $\phi(x)$) we can also consider transformation at a fixed coordinate x

i.e. for $x \rightarrow x' = \Lambda x$ consider $\phi(x) \rightarrow \phi'(x)$
⌈ not x' ⌋

doing this, we compare the field ϕ at different points!

→ Infinite-dimensional representations

$$\delta\phi = \underbrace{\phi'(x) - \phi(x)}_{\text{fixed coordinate}} \quad (\text{compare } \Delta\phi = \underbrace{\phi'(x') - \phi(x)}_{\text{fixed point}})$$

fixed coordinate

fixed point

for scalar field: $\phi'(x') = \phi(x) = \phi'(\Lambda x)$

$$\Rightarrow \phi'(x) = \phi(\Lambda^{-1}x) \rightsquigarrow \phi(x - \delta x) \quad (\text{infinitesimal})$$

$$\Rightarrow \delta\phi = \phi(x - \delta x) - \phi(x) = -\delta x^{\mu} \partial_{\mu} \phi(x)$$

for a LT $\delta x^\mu = \omega^\mu{}_\nu x^\nu$

$$\begin{aligned} \rightarrow \delta\phi &= -\omega^\mu{}_\nu x^\nu \partial_\mu \phi(x) = -\omega_{\mu\nu} x^\nu \partial^\mu \phi(x) \\ &= -\frac{1}{2} \omega_{\mu\nu} (x^\nu \partial^\mu - x^\mu \partial^\nu) \phi(x) \stackrel{!}{=} -\frac{i}{2} \omega_{\mu\nu} J_{sc}^{\mu\nu} \phi(x) \end{aligned}$$

$$\rightarrow J_{sc}^{\mu\nu} = \boxed{i(x^\mu \partial^\nu - x^\nu \partial^\mu) \equiv L^{\mu\nu}}$$

for a scalar field $J_{sc}^{\mu\nu} = L^{\mu\nu}$ exercise: they satisfy Lie algebra

for a vector field $V(x)$ $V'(x) = D(\Lambda) V(\Lambda^{-1}x)$

$$\begin{aligned} \delta V &= V'(x) - V(x) = V'(\Lambda^{-1}x) - V(x) + (V'(x) - V'(\Lambda^{-1}x)) \\ &= \underbrace{(D(\Lambda) - 1) V(x)}_{\Delta V} + \underbrace{(V'(x) - V'(\Lambda^{-1}x))}_{\text{as for scalar field}} \end{aligned}$$

$\Delta V = 0$ for scalar field but $\neq 0$ in general!

as for scalar field
↓
 $-\frac{i}{2} \omega_{\mu\nu} L^{\mu\nu} V(x)$

$$D(\Lambda) = e^{\frac{i}{2} \omega_{\mu\nu} i(g^{\mu\rho} g^{\nu\sigma} - g^{\nu\rho} g^{\mu\sigma})} \equiv S^{\mu\nu}$$

\downarrow
 $-\frac{i}{2} \omega_{\mu\nu} S^{\mu\nu}$

before $J_{sc}^{\mu\nu}$

$$\rightarrow \delta V = -\frac{i}{2} \omega_{\mu\nu} (L^{\mu\nu} + S^{\mu\nu}) \equiv -\frac{i}{2} \omega_{\mu\nu} J^{\mu\nu}$$

$i(x^\mu \partial^\nu - x^\nu \partial^\mu)$, infinite-dim representation,

$i(g^{\mu\rho} g^{\nu\sigma} - g^{\nu\rho} g^{\mu\sigma})$
4-dim representation

→ specific to vector field!

Wigner: Inf. dim rep either unitary (linear) or antiunitary (antilinear)

general:

$$J^{\mu\nu} = L^{\mu\nu} + S^{\mu\nu}$$

↑ specific for spin (as in 2.3 and 2.4)
↑ independent on nature of field

2.6. The Poincaré group

Include inhomogeneous term in LT: $x'^{\mu} = \Lambda^{\mu}_{\nu} x^{\nu} + a^{\mu}$
 2 successive Poinc trsf: $x'' = \Lambda_2 x' + a_2 = \Lambda_2 (\Lambda_1 x + a_1) + a_2$ ↑
translation

$$D(\Lambda_2, a_2) \cdot D(\Lambda_1, a_1) = D(\Lambda_2 \Lambda_1, \Lambda_2 a_1 + a_2); \quad D^{-1}(\Lambda, a) = D(\Lambda^{-1}, -\Lambda^{-1} a)$$

apart from the 6 generators $J^{\mu\nu}$ for homogeneous LT
 we also have 4 generators P^{μ} for translations

Under translation: $\phi(x) \rightarrow \phi'(x) = \phi(x-a) = e^{-i q_{\mu} P^{\mu}} \phi(x)$
↘
 scalar field $\phi'(x') = \phi'(x+a) = \phi(x)$

for infinitesimal q_{μ} : $\delta\phi = -q_{\mu} \partial^{\mu} \phi = +i q_{\mu} P^{\mu} \phi$
 $\Rightarrow P^{\mu} = i \partial^{\mu}$

Poincaré algebra

$$[J^{\mu\nu}, J^{\kappa\lambda}] = \dots \text{ as before}$$

$$[P^{\mu}, P^{\nu}] = 0$$

$$[P^{\mu}, J^{\kappa\lambda}] = i(g^{\mu\kappa} P^{\lambda} - g^{\mu\lambda} P^{\kappa})$$

This can be derived directly from

$$D(1+\omega, \epsilon) \equiv 1 + i \epsilon^{\mu} P_{\mu} - \frac{i}{2} \omega^{\mu\nu} J_{\mu\nu} \quad \rightarrow \text{exercise}$$

for infinitesimal trsf $\Lambda^{\mu}_{\nu} = g^{\mu}_{\nu} + \omega^{\mu}_{\nu}$ and $a^{\mu} = \epsilon^{\mu}$

Here, D is an infinite-dimensional unitary representation
 $\Rightarrow P_{\mu}$ and $J_{\mu\nu}$ are hermitian ↑

recall Wigner: antiunitary is also possible
 in general

Considers transformation of generators P_μ and $J_{\mu\nu}$

Since $D(\Lambda, a, \epsilon)$ is an operator, it transforms like

$$\begin{aligned} D(\Lambda, a) D(\Lambda, \omega, \epsilon) D^{-1}(\Lambda, a) &= D(\Lambda, a) D(\Lambda, \omega, \epsilon) D(\Lambda^{-1}, -\Lambda^{-1}a) \\ &= D(\Lambda, a) D((\Lambda\omega)\Lambda^{-1}, -(\Lambda\omega)\Lambda^{-1}a + \epsilon) \\ &= D(\Lambda(\Lambda\omega)\Lambda^{-1}, -\Lambda(\Lambda\omega)\Lambda^{-1}a + \Lambda\epsilon + a) \\ &= D(\Lambda\omega\Lambda^{-1}, -\Lambda\omega\Lambda^{-1}a + \Lambda\epsilon) \end{aligned}$$

This means: $D(\Lambda, a) \left(1 - \frac{i}{2} \omega_{\mu\nu} J^{\mu\nu} + i \epsilon_\mu P^\mu \right) D^{-1}(\Lambda, a)$

$$= -\frac{i}{2} (\Lambda\omega\Lambda^{-1})_{\mu\nu} J^{\mu\nu} + i (\Lambda\epsilon - \Lambda\omega\Lambda^{-1}a)_\mu P^\mu$$

compare terms $\sim \epsilon_\mu$:

$$D(\Lambda, a) i \epsilon_\mu P^\mu D^{-1}(\Lambda, a) = i \Lambda_\mu^\sigma \epsilon_\sigma P^\mu = i \Lambda_\nu^\mu \epsilon_\mu P^\nu$$

$$\Rightarrow D(\Lambda, a) P^\mu D^{-1}(\Lambda, a) = \Lambda_\nu^\mu P^\nu = (\Lambda^{-1})^\mu_\nu P^\nu$$

compare terms $\sim \omega_{\mu\nu}$

$$D(\Lambda, a) \left(-\frac{i}{2} \omega_{\mu\nu} J^{\mu\nu} \right) D^{-1}(\Lambda, a) = -\frac{i}{2} \Lambda_\mu^\sigma \omega_{\sigma\tau} (\Lambda^{-1})^\nu_\rho J^{\mu\nu} - i \Lambda_\mu^\sigma \omega_{\sigma\tau} (\Lambda^{-1})^\nu_\rho a^\nu P^\mu$$

$$= -\frac{i}{2} \Lambda_\sigma^\mu \omega_{\mu\nu} \Lambda_\kappa^\nu J^{\sigma\kappa} - i \Lambda_\sigma^\mu \omega_{\mu\nu} \Lambda_\kappa^\nu a^\kappa P^\sigma$$

$$\Rightarrow D(\Lambda, a) J^{\mu\nu} D^{-1}(\Lambda, a) = \Lambda_\sigma^\mu \Lambda_\kappa^\nu (J^{\sigma\kappa} + a^\kappa P^\sigma - a^\sigma P^\kappa)$$

For $a^\mu = 0$, P^μ is a vector

$J^{\mu\nu}$ is a tensor of rank 2

P^μ is translation invariant (not affected by q^μ)

$J^{\mu\nu}$ is not translation invariant! (compare change of ang. momentum if origin is shifted)

Consider now parity \mathcal{P} and time reversal \mathcal{T}

$\mathcal{P} \rightarrow D(\mathcal{P}, 0) \quad \mathcal{T} \rightarrow D(\mathcal{T}, 0) \quad \mathcal{P}^\mu_\nu = \begin{pmatrix} 1 & & & \\ & -1 & & \\ & & -1 & \\ & & & -1 \end{pmatrix} \quad \mathcal{T}^\mu_\nu = \begin{pmatrix} -1 & & & \\ & 1 & & \\ & & 1 & \\ & & & 1 \end{pmatrix}$

\mathcal{P}^3 transforms as follows:

$\mathcal{P} i\mathcal{P}^3 \mathcal{P}^{-1} = i\mathcal{P}^3_\nu \mathcal{P}^\nu \leftarrow \text{Notation } \mathcal{P}^3_\nu \quad \mathcal{P}^\nu \text{ mom op.}$
 $\mathcal{T} i\mathcal{P}^3 \mathcal{T}^{-1} = i\mathcal{T}^3_\nu \mathcal{P}^\nu$

want to sort out if \mathcal{P} / \mathcal{T} are unitary or antiunitary

Parity: $\mathcal{P} i\mathcal{H}\mathcal{P}^{-1} = \mathcal{P}^0_\nu i\mathcal{P}^\nu = i\mathcal{H} \quad (\text{take } \mathbf{g}=0)$

if \mathcal{P} were antiunitary, then $-\mathcal{P}\mathcal{H}\mathcal{P}^{-1} = \mathcal{H} \quad ?$
 $\rightarrow \forall$ state with energy $E > 0$ we would have a parity transf. state with $E < 0$

$\Rightarrow \mathcal{P}$ is unitary $\mathcal{P}\mathcal{H}\mathcal{P}^{-1} = \mathcal{H}$

Time reversal $\mathcal{T} i\mathcal{H}\mathcal{T}^{-1} = \mathcal{T}^0_\nu i\mathcal{P}^\nu = -i\mathcal{H}$

now we need \mathcal{T} antiunitary!

$\mathcal{T} i\mathcal{H}\mathcal{T}^{-1} = i^* \mathcal{T}\mathcal{H}\mathcal{T}^{-1} = -i\mathcal{T}\mathcal{H}\mathcal{T}^{-1} = -i\mathcal{H}$
 $\hookrightarrow \mathcal{T}\mathcal{H}\mathcal{T}^{-1} = \mathcal{H}$

Note: the theories we will consider in this course are invariant under \mathcal{P} and \mathcal{T} , i.e. their Hamiltonian \mathcal{H} satisfies $\mathcal{P}\mathcal{H}\mathcal{P}^{-1} = \mathcal{H}$ and $\mathcal{T}\mathcal{H}\mathcal{T}^{-1} = \mathcal{H}$

but not all theories respect these symmetries (electroweak interactions e.g. don't !)

From $\mathcal{P} i P^\mu \mathcal{P}^{-1} = i P^\mu_\nu P^\nu$, $\mathcal{T} i P^\mu \mathcal{T}^{-1} = i T^\mu_\nu P^\nu$

$\mathcal{P} i J^{\mu\nu} \mathcal{P}^{-1} = i P^\mu_\mu P^\sigma_\nu J^{\mu\nu}$, $\mathcal{T} i J^{\mu\nu} \mathcal{T}^{-1} = i T^\mu_\mu T^\sigma_\nu J^{\mu\nu}$

We can deduce:

$$\left. \begin{aligned} \mathcal{P} \vec{J} \mathcal{P}^{-1} &= \vec{J} && \text{axial vector!} \\ \mathcal{P} \vec{K} \mathcal{P}^{-1} &= -\vec{K} \\ \mathcal{P} \vec{P} \mathcal{P}^{-1} &= -\vec{P} \\ \mathcal{T} \vec{J} \mathcal{T}^{-1} &= -\vec{J} \\ \mathcal{T} \vec{K} \mathcal{T}^{-1} &= \vec{K} \\ \mathcal{T} \vec{P} \mathcal{T}^{-1} &= -\vec{P} \end{aligned} \right\} \text{vectors} \quad \left. \begin{aligned} & \\ & \\ & \end{aligned} \right\} \text{consistent with Poincaré algebra!}$$

To label representations, find Casimir operators

(Casimir op: an operator that commutes with all generators)

claim: $P_\mu P^\mu$ and $W_\mu W^\mu$ are Casimir op.

where $W^\mu \equiv -\frac{1}{2} \epsilon^{\mu\nu\sigma\rho} J_{\nu\sigma} P_\rho$ Pauli-Lubanski vector

'proof': $P_\mu P^\mu$ and $W_\mu W^\mu$ are LINV ($J_{\nu\sigma} \sim$ tensor of rank 2, P_σ vector \rightarrow covariance!) \Rightarrow they commute with $J^{\mu\nu}$

$$\Rightarrow [P_\mu P^\mu, J_{\kappa\sigma}] = 0 \quad \text{and} \quad [W_\mu W^\mu, J_{\kappa\sigma}] = 0$$

also $[P_\mu P^\mu, P^\kappa] = 0$ obvious and since

$$[W_\mu W^\mu, P^\kappa] = -\frac{1}{2} \epsilon^{\mu\nu\sigma\rho} [J_{\nu\sigma}, P^\kappa] P_\rho = -\frac{i}{2} \epsilon^{\mu\nu\sigma\rho} (g_\sigma^\kappa P_\nu - g_\nu^\kappa P_\sigma) P_\rho = 0$$

We also have $[W_\mu W^\mu, P^\kappa] = 0$

Considers $P_\mu P^\mu = m^2$ with $m^2 > 0$ (massive particles)

what is $W_\mu W^\mu$? \rightarrow go to rest frame $P^\mu = (m, \vec{0})$

$$W^\mu = -\frac{1}{2} m \epsilon^{\mu\nu\rho\sigma} J_{\nu\rho} \quad \rightarrow \quad W^0 = 0$$

$$W^i = \frac{m}{2} \epsilon^{0ijk} J_{jk} = m \cdot J^i$$

$$W_\mu W^\mu = -m^2 \vec{J}^2 \quad \rightarrow \quad -m^2 j(j+1)$$

for $m > 0$, rep. characterized by j , $m_j = -j, \dots, j$

states with $P^\mu = (m, 0, 0, 0)$ left invariant by rotations $\rightarrow SU(2)$

(Little group: group of transf that leaves P^μ invariant)

Consider $P_\mu P^\mu = 0$ (massless particles)

go to frame $P^\mu = (\omega, 0, 0, \omega)$

Little group: Euclidean group $E(2)$ (rotations J_z and translations in x & y direction)

naive (!!) limit $m \rightarrow 0$ from above:

$$W_\mu W^\mu = 0, \quad \text{in addition } P_\mu P^\mu = 0 \quad \text{and} \quad W_\mu P^\mu = 0$$

$$\Rightarrow W^\mu \sim P^\mu \quad \rightarrow \quad W^\mu = h \cdot P^\mu$$

$$\text{actually: } W^\mu = \omega (J^3, \underbrace{J^1 - K^2, J^2 + K^1, J^3}) = \omega \cdot \vec{J}_3 \cdot P^\mu = \frac{\vec{J} \cdot \vec{P}}{|\vec{P}|} P^\mu$$

corresponds to a continuous d.o.f.

don't seem to be realized in nature

constrain to trivial $J^1 - K^2$ and $J^2 + K^1$

\uparrow
helicity h

→ not all possible representations seem to play a role in nature !?

There are further representations without known interpretations (some with continuous spin)

summary of what we need:

Vacuum: $P^\mu = 0$, little group $SO(3,1)$ (trivial)

massive particles $P^2 = m^2 > 0, p^0 > 0$
↳ $k^\mu = (m, 0, 0, 0)$ little group $SO(3)$

additional characterization by spin \rightarrow $(2s+1)$ states

massless particles $P^2 = 0, p^0 > 0$
↳ $k^\mu = (\omega, 0, 0, \omega)$ little group $E(2)$

additional characterization by helicity

$$h = \frac{\vec{P} \cdot \vec{J}}{|\vec{P}|} = \pm 1 \cdot |\vec{J}|$$

Note h is pseudo scalar (changes sign under parity \mathcal{P})

→ In parity conserving theories combine $h \pm |\vec{J}|$ states! 2 states